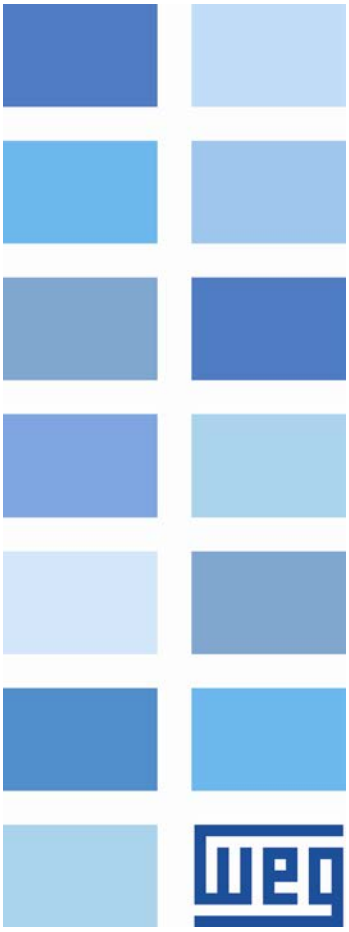
SoftPLC

CFW500

User's Manual



Phone: 800.894.0412 - Fax: 888.723.4773 - Web: www.ctiautomation.net - Email: info@ctiautomation.net

SoftPLC Manual

Series: CFW500

Language: English

Document Number: 10002299985 / 01

Publication Date: 06/2015

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ABOUT THE MANUAL

This manual provides the required information for the operation of the CFW500 frequency inverter using the user's programming module, called SoftPLC. This manual must be used together with the user's manual of the CFW500 and WLP software.

ABBREVIATIONS AND DEFINITIONS

PLC	Programmable Logic Controller
CRC	Cycling Redundancy Check
RAM	Random Access Memory
WLP	Ladder Language Programming Software
USB	Universal Serial Bus

NUMERICAL REPRESENTATION

Decimal numbers are represented by means of digits without suffix. Hexadecimal numbers are represented with the letter 'h' after the number.

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1 INTRODUCTION TO SOFTPLC

The SoftPLC is a resource that adds the functionalities of a PLC to the CFW500, providing the product with flexibility and allowing the user to develop its own applications (user's programs).

The main SoftPLC characteristics are:

- Programming in "Ladder Language" using the WLP software.
- Access to all Parameters and I/Os of the CFW500.
- 50 configurable parameters for the user's use.
- PLC, Mathematical and Control Blocks
- On-line transfer and monitoring of the software application via Serial/USB interface.
- Transfer of the application software installed on the CFW500 to the PC with password restriction.
- Storage of the software application on the FLASH memory board.
- Execution directly on the RAM.

1.1 SYMBOL OF THE DATA TYPES

%KW word-type constants (16 bits)
%KF float type constants (32 bits, floating point)
%MX bit markers
%MW word markers (16 bits)
%MF float markers (32 bits, floating point)
%SX system bit markers
%SW system word markers (16 bits)
%IX digital Inputs
%IW analog inputs (16 bits)
%QX digital outputs
%QW analog outputs (16 bits)
%UW user parameters (16 bits)
%UW user parameters (16 bits)
%PD drive parameter (16 bits)

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2 SOFTPLC MEMORY

The total size of the SoftPLC parameter is 7684 bytes for program memory and data memory.

NOTE!
The SoftPLC application is stored in the memory of the plug-in used at the moment of download. Therefore, if the plug-in is changed, it will be necessary to download the application again.

2.1 MEMORY

- SoftPLC function: 7684 bytes
- SoftPLC User Parameter: 508 bytes

2.2 DATA MEMORY

The SoftPLC data memory area (user variables) is shared with the programming memory. Therefore, the total size of an application may vary as a function of the number of variables applied by the user.

The bit, word and float markers are allocated according to the LAST address used on the application, that is, the longer the last address, the larger the allocated area. Therefore, it is recommended to use the markers in a SEQUENTIAL manner.

The word and float constants do also use program memory space.

2.2.1 Constants

Table 2.1: *Constant Memory Map*

Sym.	Description	Bytes
%KW	Word Constants (16 bits)	It depends on the number of different word constants. E.g.: If there were used: - %KW: 327 = 2 bytes - %KW: 5; 67 = 4 bytes - %KW: 13; 1000; ~~13~~; 4 = 6 bytes
%KF	Float Constants (32 bits – IEEE)	It depends on the number of different float constants. E.g.: If there were used: - %KF: -0,335 = 4 bytes - %KF: 5,1; 114,2 = 8 bytes - %KF: 0,0; 115,3; ~~0,0~~; 13,333 = 12 bytes

2.2.2 Physical Inputs and Outputs (Hardware)

Table 2.2: *I/O Memory Map*

Sym.	Description	Range	Bytes
%IX	Digital Inputs	1 ... 8	2
%QX	Digital Outputs	1 ... 5	2
%IW	Analog Inputs/Frequency	1 ... 4	8
%QW	Analog Outputs/Frequency	1 ... 3	6

NOTE!
The %IW4 marker corresponds to the frequency input. In order to activate this input, it is necessary to set P0246 to 1.

NOTE!
The %QW3 marker corresponds to the frequency output. In order to activate this output, it is necessary to set P0257 according to the desired function. Furthermore, note that the DO2 circuit is configured in open collector.

NOTE!
The values of the Analog/Frequency Inputs (%IW) and of the Analog/Frequency Outputs (%QW) respectively read and written via SoftPLC respect their gains (P0232, P0237, P0242, P0247: %IW1–%IW4 and P0252, P0255, P0258: %QW1–%QW3) and offsets (P0234, P0239, P0244, P0249: %IW1–%IW4).

NOTE!
The values read or written via SoftPLC obey the following rules, respecting the parameters related to the analog input and output signal types (P0233, P0238, P0243: %IW1–%IW3 and P253, P256: %QW1–%QW2):

- Option: 0 to 10V/20mA
  - 0V or 0mA = 0
  - 10V or 20mA = 32767
- Option: 4 to 20mA
  - 4mA = 0
  - 20mA = 32767
- Option: 10V/20mA to 0
  - 10V or 20mA = 0
  - 0V or 0mA = 32767
- Option: 20 to 4mA
  - 20mA = 0
  - 4mA = 32767

2.2.3 Volatile Markers (Variables)

They consist of variables that can be applied by the user to execute the applicative logics. They can be bit markers (1 bit), word markers (16 bit) or float markers (32 bit – IEEE).

Table 2.3: *Volatile Marker Memory Map*

Sym.	Description	Range	Bytes
%MX	Bit Markers	5000 ... 6099	It depends on the last used marker. They are organized in byte pairs. E.g.: - last marker: %MX5000 = 2 bytes - last marker: %MX5014 = 2 bytes - last marker: %MX5016 = 4 bytes - last marker: %MX5039 = 6 bytes
%MW	Word Markers	8000 ... 8199	It depends on the last used marker. E.g.: - last marker: %MX8000 = 2 bytes - last marker: %MX8001 = 4 bytes - last marker: %MX8007 = 16 bytes
%MF	Float Markers	9000 ... 9199	It depends on the last used marker. E.g.: - last marker: %MX9000 = 4 bytes - last marker: %MX9001 = 8 bytes - last marker: %MX9007 = 32 bytes

NOTE!
In order to minimize the application size, use the markers in a sequential manner.
E.g.:

- Bit markers: %MX5000, %MX5001, %MX5002, ...
- Word markers: %MW8000, %MW8001, %MW8002, ...
- Float markers: %MF9000, %MF9001, %MF9002, ...

2.2.4 System Markers

They consist of special variables that allow the user to read and change inverter data that may or may not be available in the parameters. They can be: system bit markers (1 bit) or system word markers (16 bits).

Table 2.4 (a): *Memory Map for the Odd System Bits – Writing/Command*

Sym.	Description		Range	Bytes
Type	System Bits		3000 ... 3040	4 bytes
%SX	*Writing/Command (odd)*			
	3001	General Enabling		**0:** It disables the inverter completely, interrupting the supply for the motor. **1**: It enables the inverter, allowing the motor operation.
	3003	Run/Stop		**0**: It stops the motor with deceleration ramp. The motor rung according to the acceleration ramp until reaching the speed reference value.
	3005	Speed Direction		**0**: It runs the motor in the counterclockwise direction. **1:** It runs the motor in the clockwise direction.
	3007	JOG		**0**: It disables the JOG function. **1**: It enables the JOG function.
	3009	LOC/REM		**0:** The inverter goes to the local situation. **1**: The inverter goes to the remote situation.
	3011	Fault reset		**0**: No function. **1:** If in fault condition, it resets the inverter**.** **NOTE:** When this command is executed, the inverter and the SoftPLC Application are reinitialized. This is also valid for reset via keypad.
	3021	Activates the Second Ramp		**0:** The values for the motor acceleration and deceleration are those from the first Ramp (P0100 and P0101). **1:** The values for the motor acceleration and deceleration are those from the second Ramp (P0102 and P0103). **Note:** Program P0105 in 6 in order to enable the selection via SoftPLC.

Table 2.4 (b): *Memory Map for the Even System Bit – Reading/State*

Sym.	Description		Range	Bytes
Type	System Bits		3000 ... 3040	4 bytes
%SX	*Reading/State (Even)*			
	3000	General Enabling		**0:** General enabling is not active. **1:** General enabling is active and the inverter is ready to run the motor.
	3002	Motor Running (RUN)		**0:** The motor is stopped. **1:** The inverter is driving the motor at the set point speed, or executing either the acceleration or the deceleration ramp.
	3004	Speed Direction		**0:** The motor is rotating counterclockwise. **1:** The motor is rotating clockwise.
	3006	JOG		**0:** JOG function inactive**.** **1:** JOG function active.
	3008	LOC/REM		**0**: Inverter in local mode**.** **1:** Inverter in remote mode.
	3010	In Fault		**0:** Inverter is not in fault state**.** **1:** Some fault registered by the inverter**.** **Note:** The number of the fault can be read through parameter P0049 – Current Fault.
	3012	Undervoltage		**0:** No undervoltage**.** **1:** With undervoltage.
	3014	PID Operation Mode		**0**: In manual mode (PID function). **1:** In automatic mode (PID function).
	3016	Alarm Condition		**0:** Inverter is not in an alarm condition. **1:** Inverter is in an alarm condition. **Note:** The number of the alarm can be read by means of parameter P0048 – Current Alarm.
	3018	In Configuration Mode		**0**: Inverter operating normally. **1:** Inverter in configuration state. It indicates a special condition when the inverter cannot be enabled: - Executing the self tuning routing. - There is a parameter setting incompatibility. **Note:** Parameter P0047 shows the cause of the parameter setting incompatibility.
	3020	Active Ramp		**0:** It indicates that the first Ramp is active. **1**: It indicates that the second Ramp is active.
	3032	Start key (1)		**0:** Not pressed. **1:** Pressed during 1 scan cycle
	3034	Stop key (0)		
	3036	Speed direction key (↻)		
	3038	Local/Remote key		
	3040	JOG key		**0:** Not pressed. **1:** Pressed**.**

Table 2.5: *Memory Map for the Even System Word Markers*

Sym.	Description		Range	Bytes
%SW	System Words		3300 ... 3324	48 bytes
	Reading Markers/Status (Even)			
	3300	Motor speed [13 bits]		
	3302	Motor synchronous speed [rpm]		
	3304	Motor speed [rpm]		
	3306	Speed reference [rpm]		
	3308	Alarm		
	3310	Fault		
	3320	Inverter rated current [A x10]		
	3322	Unfiltered motor current (P003) [A x10]		
	3324	Unfiltered motor torque [% x10]		

NOTE!
The system word markers %SW3300 use a 13-bits resolution (8192 ⟶ 0 to 8191), which the motor synchronous speed. Thus, if the speed reference via "Reference" block (%SW3301) is 4096 for a VI pole motor (this means a synchronous speed of 1200 rpm), the motor will run at 600 rpm.

NOTE!
Equation for the calculation of the motor speed in rpm:

$$\text{Speed in rpm} = \frac{\text{synchronous speed in rpm x speed in 13 bits}}{8192}$$

NOTE!
Equation for the calculation of the motor speed in Hz:

$$\text{Speed in Hz} = \frac{\text{synchronous frequency in Hz (P0403) x speed in 13 bits}}{8192}$$

2.2.5 Parameters

The parameters from P1010 to P1059 appear on the keypad only when there is a valid application (user program) in the memory, i.e., when P1000 > 0.

Table 2.6: *Parameter Memory Map*

Sym.	Description	Range	Bytes
%PD	System Parameters (refer to the CFW500 manual)	0... 999	
%PW	SoftPLC Parameters	1000 ... 1059	6 bytes
	P1000: SoftPLC Status [Read-only parameter]	0: No application 1: Install. Applic. 2: Incompat. App. 3: App. Stopped 4: App. Running	
	P1001: SoftPLC Command	0: Stop Program 1: Run Program 2: Delete Program	
	P1002: Scan Cycle Time [ms] [Read-only parameter]		
%UW	User Parameters	1010 ... 1059	100 bytes

2.3 MODBUS

2.3.1 Modbus protocol SoftPLC addresses

Table 2.7: *SoftPLC x Modbus Address Range*

Sym.	Description	SoftPLC	MODBUS
%IX	Digital Inputs	1 ... 8	2201...2208
%QX	Digital Outputs	1 ... 5	2401...2405
%IW	Analog Inputs/Frequency	1 ... 4	2601...2603
%QW	Analog Outputs/Frequency	1 ... 3	2801...2802

NOTE!
The %IW4 marker corresponds to the frequency input. In order to activate this input, it is necessary to set P0246 to 1.

NOTE!
The %QW3 marker corresponds to the frequency output. In order to activate this output, it is necessary to set P0257 according to the desired function. Furthermore, note that the DO2 circuit is configured in open collector.

NOTE!
All the other data types have the user addresses (SoftPLC) equal to the Modbus addresses. E.g.: %PD0100 = Modbus address 100; %MX5000 = Modbus address 5000; %SW3308 = Modbus address 3308.

2.3.2 Protocol

Refer to the RS232/RS485 Serial Communication manual, at the Modbus Protocol chapter.

3 RESUME OF THE FUNCTION BLOCKS

This chapter contains a summary of the function blocks that are available for the user programming.

3.1 CONTACTS

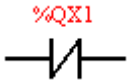
They send to the stack the content of a programmed data (0 or 1), which can be of the following type:

- %MX: Bit Marker
- %IX: Digital Input
- %QX: Digital Output
- %UW: User Parameter
- %SX: System Bit Marker – Reading

3.1.1 Normally Open Contact – NO CONTACT

Menu: *Insert-Contacts-NO CONTACT.*
E.g.: It sends to the stack the content of bit marker 5000.

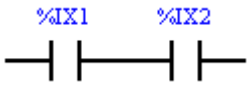
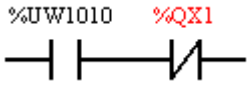
3.1.2 Normally Closed Contact – NC CONTACT



Menu: *Insert-Contacts-NC CONTACT.*
E.g.: It sends to the stack the negated content of digital output 1.

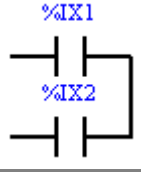
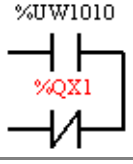
3.1.3 AND Logic with Contacts

When the contacts are in series, an AND logic is executed among them, storing the result in the stack. Examples:

Example	Truth Table		
 %IX1.%IX2	%IX1	%IX2	Stack
	0	0	0
	0	1	0
	1	0	0
	1	1	1
 %UW1010. (~%QX1)	%UW1010	%QX1	Stack
	0	0	0
	0	1	0
	1	0	1
	1	1	0

3.1.4 OR Logic with Contacts

When the contacts are in parallel, an OR logic is executed among them, storing the result in the stack. Examples:

Example	Operation	Truth Table		
	%IX1 + %IX2	%IX1	%IX2	Stack
		0	0	0
		0	1	1
		1	0	1
		1	1	1
	%UW1010 + (~%QX1)	%UW1010	%QX1	Stack
		0	0	1
		0	1	0
		1	0	1
		1	1	1

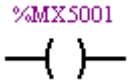
3.2 COILS

They save the content of the stack on the programmed data (0 or 1), which can be of the following type:

- %MX: Bit Marker
- %QX: Digital Output
- %UW: User Parameter
- %SX: System Bit Marker – Writing

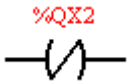
It is allowed to add coils in parallel at the last column.

3.2.1 Normal Coil - COIL



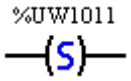
Menu: *Insert-Coils-COIL*
E.g.: It sets the bit marker 5001 with the stack content

3.2.2 Negated Coil – NEG COIL



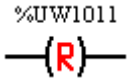
Menu: *Insert-Coils-NEG COIL*
E.g.: It sets the digital output 2 with the negated content of the stack

3.2.3 Set Coil – SET COIL



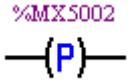
Menu: *Insert-Coils-SET COIL*
E.g.: It sets the user parameter 1011, provided that the content of the stack is not 0

3.2.4 Reset Coil – RESET COIL



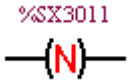
Menu: *Insert-Coils-RESET COIL*
E.g.: It resets the user parameter 1011, provided that the content of the stack is not 0

3.2.5 Positive Transition Coil – PTS COIL



Menu: *Insert-Coils-PTS COIL*
E.g.: It sets the bit marker 5002 during 1 scan cycle, provided that a transition from 0 to 1 in the stack is detected.

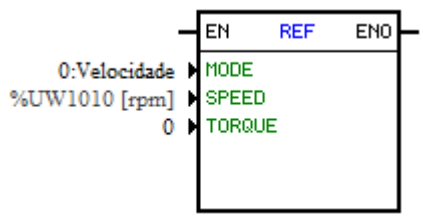
3.2.6 Negative Transition Coil – NTS COIL



Menu: *Insert-Coils-NTS COIL*
E.g.: It sets the system bit marker 3011 during 1 scan cycle, provided that a transition from 1 to 0 in the stack is detected.

3.3 MOVEMENT BLOCKS

3.3.1 Speed and/or Torque Reference – REF

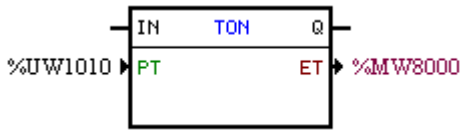


Menu: *Insert-Function Blocks-Movement-REF*
Input:
EN: Enables block
Output:
ENO: Goes to 1 when EN ≠ 0 and without error
Properties:
MODE: 0=Speed Mode
SPEED: Speed reference [RPM,13 Bits, Hz (x10)]
TORQUE: Not available

In the example above, if the EN is active, and the digital input 1 is off, then the block will generate a speed reference according to the user parameter 1010 in the rpm unit. If there is no error (example: disabled inverter), the ENO output goes to 1.

3.4 PLC BLOCKS

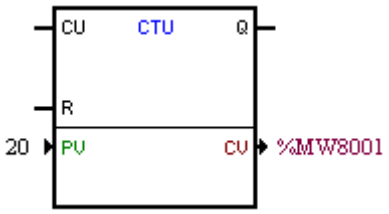
3.4.1 Timer – TON



Menu: *Insert-Function Blocks-PLC-TON*
Input:
IN: Enables the block
Output:
Q: Goes to 1 when IN ≠ 0 and ET ≥ PT
Properties:
PT: Programmed time *(Preset Time)*
ET: Elapsed Time

In the example above, if the IN input is active and the content of the word marker 8000 is greater than or equal to the content of the user parameter 1010, the output Q is set.

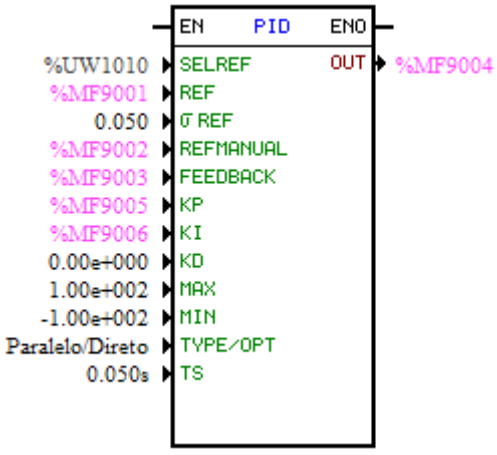
3.4.2 Incremental Counter – CTU



Menu: *Insert-Function Blocks-PLC-CTU*
Inputs:
CU: Captures the transitions from 0 to 1 at this input (*Counter Up*)
R: Resets CV
Output:
Q: Goes to 1 when CV ≥ PV
Properties:
PV: Programmed value *(Preset Value)*
CV: Counter Value *(Counter Value)*

In the example above, if the content of the word marker 8001 is greater than or equal to 20, the output Q is set.

3.4.3 Proportional-Integral-Derivative Controller – PID

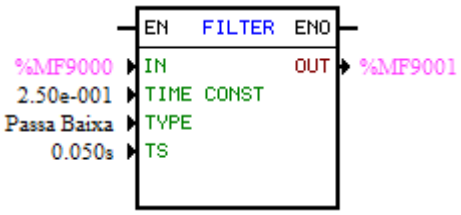


Menu: *Insert-Function Blocks-PLC-PID*
Inputs:
EN: Enables the block
Output:
ENO: EN Input image
Properties:
TS: Sampling time
SELREF: Automatic/manual reference
REF: Automatic reference
δREF: Time constant of the automatic reference filter
REFMANUAL: Manual reference
FEEDBACK: Process feedback
KP: Proportional gain
KI: Integral gain
KD: Derivative gain
MAX: Maximum output value
MIN: Minimum output value
TYPE: Academic/parallel
OPT: Direct/reverse
OUT: Controller output

In the example above, if the input EN is active, the controller starts its operation. The content of the user parameter 1010 selects the reference that is active, that is, whether it is the float marker 9001 (automatic reference) or 9003 (manual reference). There is a 0.05s filter for the automatic reference. Since the derivative gain is fixed in 0, this indicates that de PID was converted into a PI. The value of the control output OUT,

represented by the float marker 9004, has the maximum and minimum limits of 100 and -100 and the sampling time of 0.050s.

3.4.4 Low-pass or High-pass Filter – FILTER

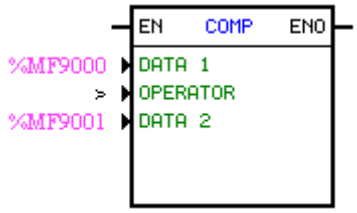


Menu: *Insert-Function Blocks-PLC-FILTER*
Inputs:
EN: Enables the block
Output:
ENO: EN Input image
Properties:
TS: Sampling time
IN: Input data
TIMECONST: Filter time constant
TYPE: Low-pass/High-pass
OUT: Input data filtered value

In the example above, if the EN input is active, the content of the float marker 9000 will be filtered with a time constant of 0.25s by a low-pass and filter and will be transferred to the float marker 9001.

3.5 CALCULATION BLOCKS

3.5.1 Comparator – COMP

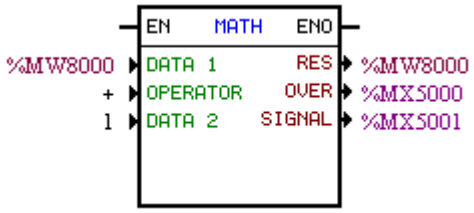


Menu: *Insert-Function Blocks-Calculation-COMP*
Input:
EN: Enables the block
Output:
ENO: Goes to 1 when the comparison condition is fulfilled
Properties:
FORMAT: Integer or floating point
DATA 1: Comparison data 1
OPERATOR: Comparison operator
DATA 2: Comparison data 2

In the example above, if the EN input is active and the content of the float marker 9000 is greater than the float marker 9001, then the output ENO is set.

NOTE!
If FORMAT is integer, all the numerical data are considered words of 15 bits + signal (-32768 to 32767).

3.5.2 Math Operation – MATH



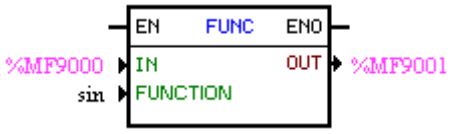
Menu: *Insert-Function Blocks-Calculation-MATH*
Input:
EN: Enables the block
Output:
ENO: Indicates if the calculation has been executed
Properties:
FORMAT: Integer or floating point
DATA1: Calculation Data 1. It may also appear as DATA1H and DATA1L (representing the high and low parts of data 1)
OPERATOR: Mathematic operator (+, -, *, etc)
DATA2: Calculation Data 2. It may also appear as DATA2H and DATA2L (representing the high and low parts of data 2)
RES: Calculation result. It may also appear as RESH and

	RESL (representing the high and low parts of the result) and also as QUOC and REM (representing the quotient and remainder of a division)
OVER:	Indicates if the result exceeded its limit
SIGNAL:	Result sign

In the example above, when the input EN is active, the value of the word marker 8000 is incremented at each scan cycle. When the bit marker 5000 goes to 1, it indicates overflow and the word marker 8000 remains in 32767.

NOTE!
If FORMAT is integer, all the numerical data are considered words of 15 bits + sign (-32768 to 32767).

3.5.3 Math Function - FUNC

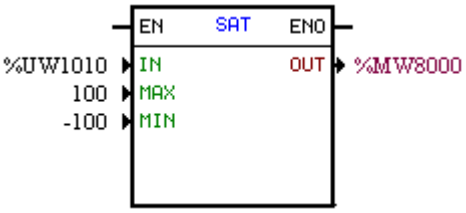


Menu: *Insert-Function Blocks-Calculation-FUNC*
Input:
EN: Enables the block
Output:
ENO: Indicates if the calculation has been executed
Properties:
FORMAT: Integer or floating point
IN: Data to be calculated
FUNCTION: Mathematic function (sin, cos, etc)
OUT: Calculation result

In the example above, when the EN input is active, the float marker 9001 presents the result of the float marker 9000 sine calculation.

NOTE!
If FORMAT is integer, all the numerical data are considered words of 15 bits + sign (-32768 to 32767).

3.5.4 Saturator – SAT



Menu: *Insert-Function Blocks-Calculation-SAT*
Input:
EN: Enables the block
Output:
ENO: Indicates if saturation has occurred, provided that EN ≠ 0
Properties:
FORMAT: Integer or floating point
IN: Input data
MAX: Maximum allowed value
MIN: Minimum allowed value
OUT: Output data

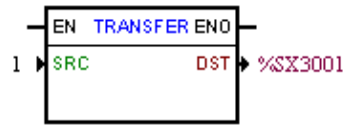
In the example above, when the EN input is active, the word marker 8000 contains the user parameter 1010 value, but limited between the maximum of 100 and the minimum of -100.

NOTE!
If FORMAT is integer, all the numerical data are considered words of 15 bits + sign (-32768 to 32767).

NOTE!
If the value of MIN is greater than the MAX, the outputs OUT and ENO are reset to zero.

3.6 TRANSFER BLOCKS

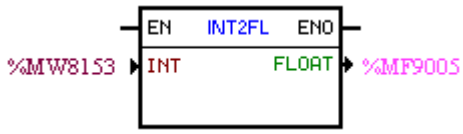
3.6.1 Data Transfer – TRANSFER



Menu: *Insert-Function Blocks-Transfer-TRANSFER*
Input:
EN: Enables the block
Output:
ENO: Indicates that the transfer has been done
Properties:
SRC: Source data
DST: Destine data

In the example above, if the EN input is active, the word constant 1 is transferred to the system bit marker 3001 (general enable).

3.6.2 Conversion from Integer (16 bits) to Floating Point – INT2FL

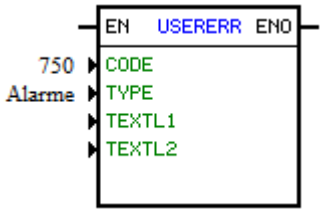


Menu: *Insert-Function Blocks-Transfer-INT2FL*
Input:
EN: Enables the block
Output:
ENO: Indicates that the transfer has been done
Properties:
INT: Integer data
FLOAT: Data converted into floating point

In the example above, if the EN input is active, the content of word marker 8153 (taking into account its sign) is converted to floating point to the float marker 9005.

NOTE!
INT is treated as word of 15 bits + sign (-32768 to 32767).

3.6.3 User Fault or Alarm Generator - USERERR

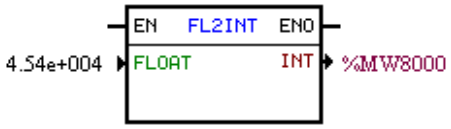


Menu: *Insert-Function Blocks-Transfer-USERERR*
Input:
EN: Enables the block
Output:
ENO: It indicates 1 when EN = 1 and the alarm or error has been effectively generated.
Properties:
CODE: Fault or alarm code.
TYPE: 0: Generates alarm, 1: Generates fault
TEXTL1: HMI line 1 text (Not available)
TEXTL2: HMI line 2 text (Not available)

In the example above, if the EN input is active, A750 will appear.

NOTE!
If this block is configured as Fault, it is necessary to reset the drive so as to enable it again.

3.6.4 Convert from Floating Point to Integer (16 bits) – FL2INT

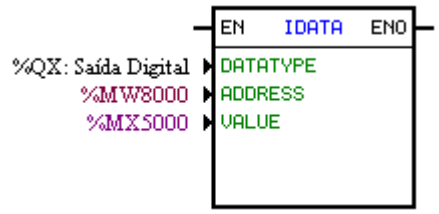


Menu: *Insert-Function Blocks-Transfer-FL2INT*
Input:
EN: Enables the block
Output:
ENO: Indicates that the transfer has been done
Properties:
FLOAT: Floating point data
INT: Data converted into integer

In the example above, if the EN input is active, the float constant $4.54x10^4$ is converted into an integer with sign via word marker 8000. However, after the conversion, the word marker 8000 will remain with the value 32767, because this is the positive limit for a Word.

NOTE!
INT is treated as word of 15 bits + sign (-32768 to 32767).

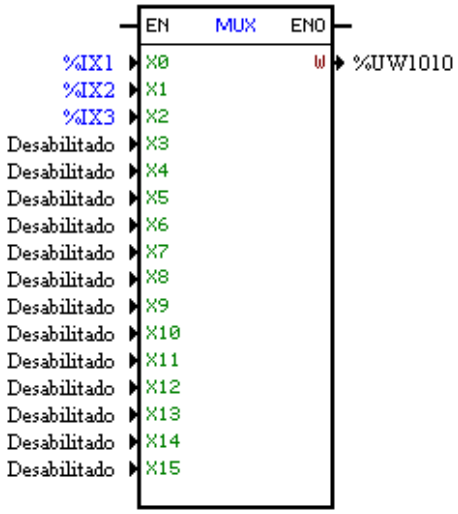
3.6.5 Indirect Data Transfer – IDATA



Menu: *Insert-Function Blocks-Transfer-IDATA*
Input:
EN: Enables the block
Output:
ENO: Indicates that the transfer has been done
Properties:
CMD: Read/Write command
DATATYPE: Data type
ADDRESS: User address
VALUE: Read content/Value to be written

In the example above, if the EN input is active, the content of the bit marker 5000 is written to the digital output whose address is the content of the word marker 8000.

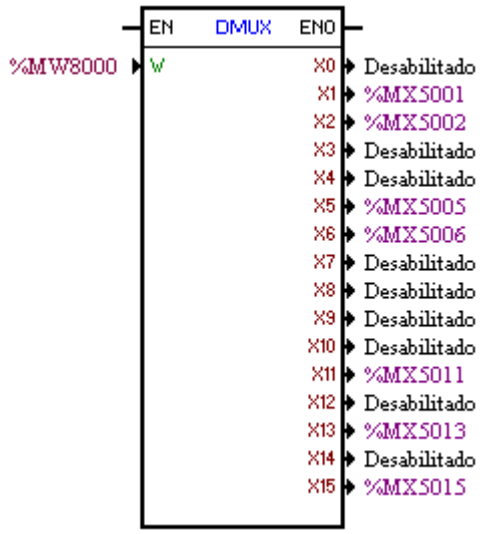
3.6.6 Multiplex – MUX



Menu: *Insert-Function Blocks -Transfer-MUX*
Input:
EN: Enables the mathematic operation
Output:
ENO: Indicates that the transfer has been done
Properties:
X0-X15: Binary data vector
W: Resulting word

In the example above, when the EN input is active, the digital inputs 1, 2 and 3 transfer their content to the bits 0, 1 and 2 of the user parameters P1010.

3.6.7 Demultiplexer – DMUX



Menu: *Insert-Function Blocks-Transfer-DMUX*
Input:
EN: Enables the mathematic operation
Output:
ENO: Indicates that the transfer has been done
Properties:
W: Source word
X0-X15: Resulting binary data vector

In the above example, when the EN input is active, the bits 1, 2, 5, 6, 11, 13 and 15 of the word marker 8000 are transferred respectively to the bit markers 5001, 5002, 5005, 5006, 5011, 5013 and 5015.

4 INVERTER PARAMETER SETTINGS

In the continuation, only the parameters of the CFW500 frequency inverter that are related to the SoftPLC will be presented.

4.1 SYMBOLS FOR PROPERTY DESCRIPTION

RO	Read-only parameter.
CFG	Parameter that can be changed only with a stopped motor.
Net	Parameter visible on the keypad if the inverter has a network interface installed – RS232, RS485, CAN, Profibus – or if the USB interface is connected.
Serial	Parameter visible on the keypad if the inverter has the RS232 or RS485 interface installed.
USB	Parameter visible on the keypad if the inverter USB interface is connected.

4.2 CFW500 CONFIGURATION PARAMETERS

P0100 – ACCELERATION TIME

P0101 – DECELERATION TIME

P0220 – LOCAL/REMOTE SELECTION SOURCE

P0221 – SPEED REFERENCE SELECTION – LOCAL SITUATION

P0222 – SPEED REFERENCE SELECTION – REMOTE SITUATION

P0223 – FORWARD/REVERSE SELECTION – LOCAL SITUATION

P0226 – FORWARD/REVERSE SELECTION – REMOTE SITUATION

P0224 – RUN/STOP SELECTION – LOCAL SITUATION

P0227 – RUN/STOP SELECTION – REMOTE SITUATION

P0225 – JOG SELECTION – LOCAL SITUATION

P0228 – JOG SELECTION – REMOTE SITUATION

P0246 – FREQUENCY INPUT FI

P0251 – AO1 FUNCTION

P0254 – AO2 FUNCTION

P0276 – DO2 FUNCTION

P0263 – DI1 FUNCTION

P0264 – DI2 FUNCTION

P0265 – DI3 FUNCTION

P0266 – DI4 FUNCTION

P0267 – DI5 FUNCTION

P0268 – DI6 FUNCTION

P0269 – DI7 FUNCTION

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P0270 – DI8 FUNCTION

P0271 – DIGITAL INPUT SING

P0275 – DO1 FUNCTION (RL1)

P0276 – DO2 FUNCTION (RL2)

P0277 – DO3 FUNCTION (RL3)

P0278 – DO4 FUNCTION

P0279 – DO5 FUNCTION

NOTE!
The resources of available inputs and outputs depend on the used plug-in module.
For further information, please, refer to the CFW500 Programming Manual.

4.3 SOFTPLC EXCLUSIVE PARAMETERS

P1000 – SoftPLC STATUS

Adjustable Range:	0 = No Application 1 = Install. App. 2 = Incompat. App. 3 = App. Stopped 4 = App. Running	**Factory Setting:** 0

Properties: RO
Access groups via HMI:

01 PARAMETER GROUPS
∟ 50 SoftPLC

Description:
It allows the user to view SoftPLC status. If there are no applications installed, the parameters P1001 to P1059 will not be shown on the keypad.

If this parameter presents the option 2 (“Incompat. App.”), it indicates that the version that has been loaded in the flash memory board is not compatible with the current CFW500 firmware.

In this case, it is to recompile the project in the WLP, considering the new CFW500 version and download it again. If that is not possible, the upload of this application can be done with the WLP, provided that the application password is known or is not enabled.

P1001 – SoftPLC COMMAND

Adjustable Range:	0: Stop Program 1 = Run Program 2 = Delete Program	**Factory Setting:** 0

Properties: CFG
Access groups via HMI:

01 PARAMETER GROUPS
∟ 50 SoftPLC

Description:
It allows stopping, running or excluding an installed application, but the motor must be disabled in order to do so.

P1002 – SCAN CYCLE TIME

Adjustable Range: 0.00 to 99.99 s

Factory Setting: Not applicable

Properties: RO

Access groups via HMI:

01 PARAMETER GROUPS
∟ 50 SoftPLC

Description:
It consists of the application scanning time. The larger the application, the longer the scanning time.

P1010 to P1059 – SoftPLC USER PARAMETERS

Adjustable Range: 0 to 65535

Factory Setting: 0

Properties: -

Access groups via HMI:

01 PARAMETER GROUPS
∟ 50 SoftPLC

Description:
They consist of use parameters defined by the user via WLP software, as described in item 5.5.

NOTE!
The parameters P1010 to P1019 can be viewed in the monitoring mode.

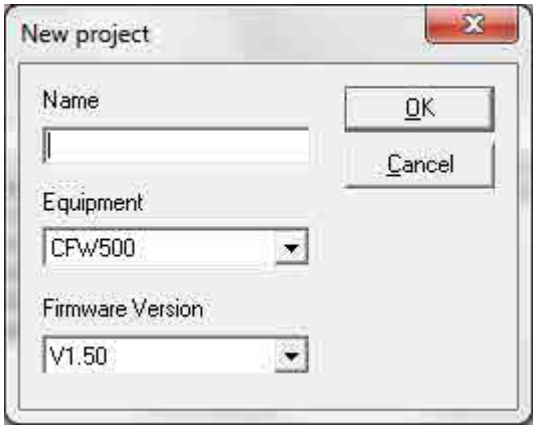
NOTE!
When parameter P1011 is a writing parameter and it is programmed in P0205, P0206 or P0207, then its content can be changed with the HMI keys and .

5 SUMMARY OF THE WLP MAIN FUNCTIONS

This chapter brings basic information about the operations done with the WLP software for the use of the CFW500 inverter. More information can be obtained in the help of the WLP software

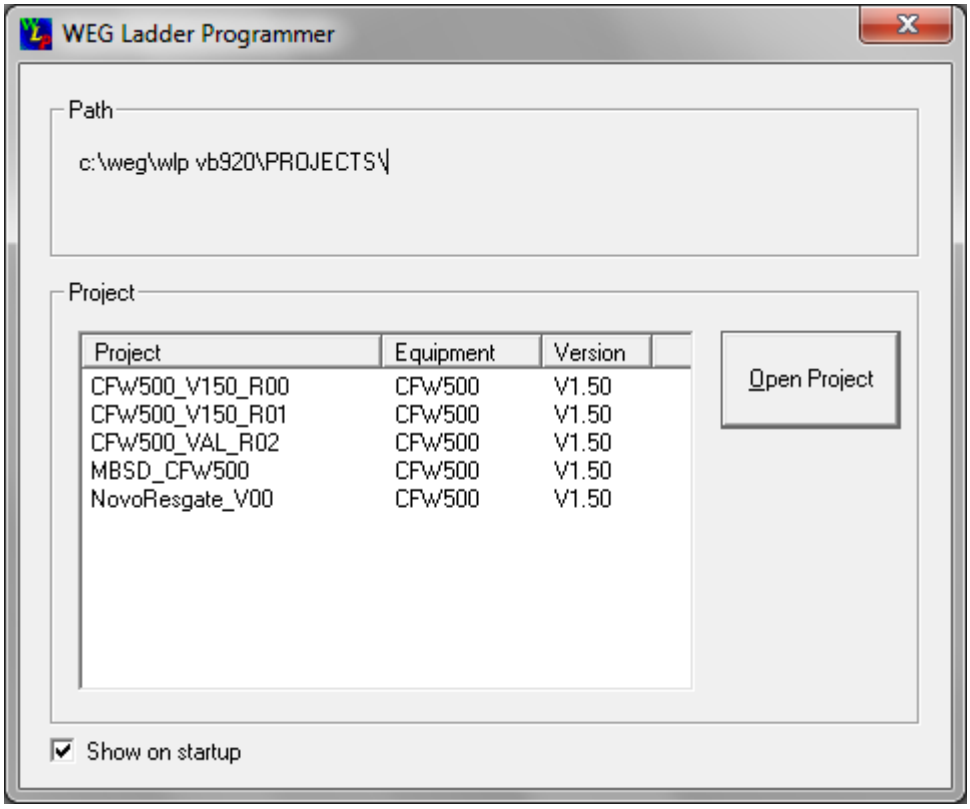
5.1 PROJECT – NEW

It creates a new project. Besides defining the project name, it is also necessary to configure the equipment and the respective firmware version.



5.2 PROJECT – OPEN

It opens the selected project.



5.3 PROJECT – PROPERTIES

It allows the user to define the equipment and firmware version. In this box, it is also configure whether or not the project will have upload password.

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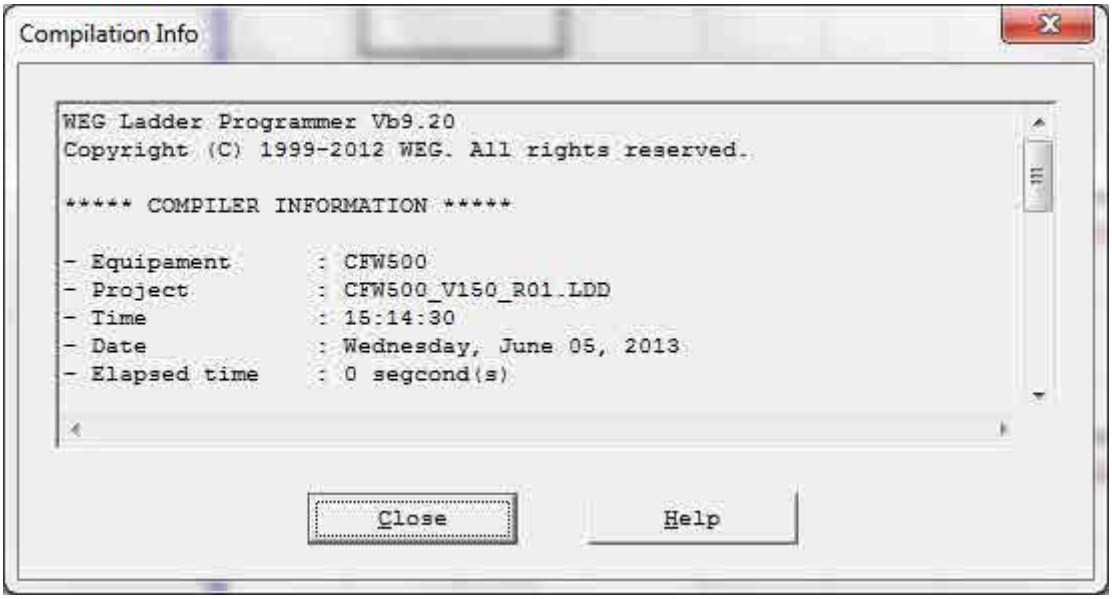
5.4 VIEW – COMPILATION INFORMATION

It allows the user to know the compile application size in bytes (<projectname>.bin) to be sent to the equipment.

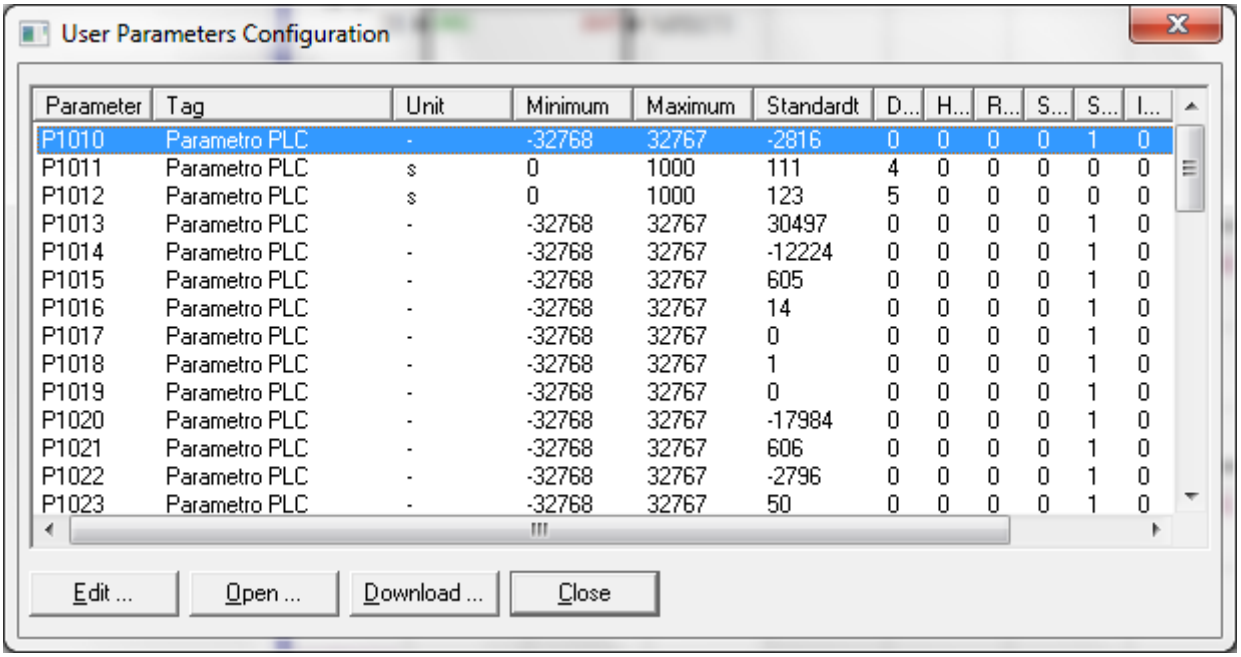

Compilation Info
WEG Ladder Programmer Vb9.20
Copyright (C) 1999-2012 WEG. All rights reserved.
***** COMPILER INFORMATION *****
- Equipament : CFW500
- Project : CFW500_V150_R01.LDD
- Time : 15:14:30
- Date : Wednesday, June 05, 2013
- Elapsed time : 0 segcond(s)
Close
Help

5.5 VIEW – USER PARAMETER CONFIGURATION

It opens an attribute visualization window for all the user parameters. With double click on the parameter, it is permitted the configuration of these attributes, which include:

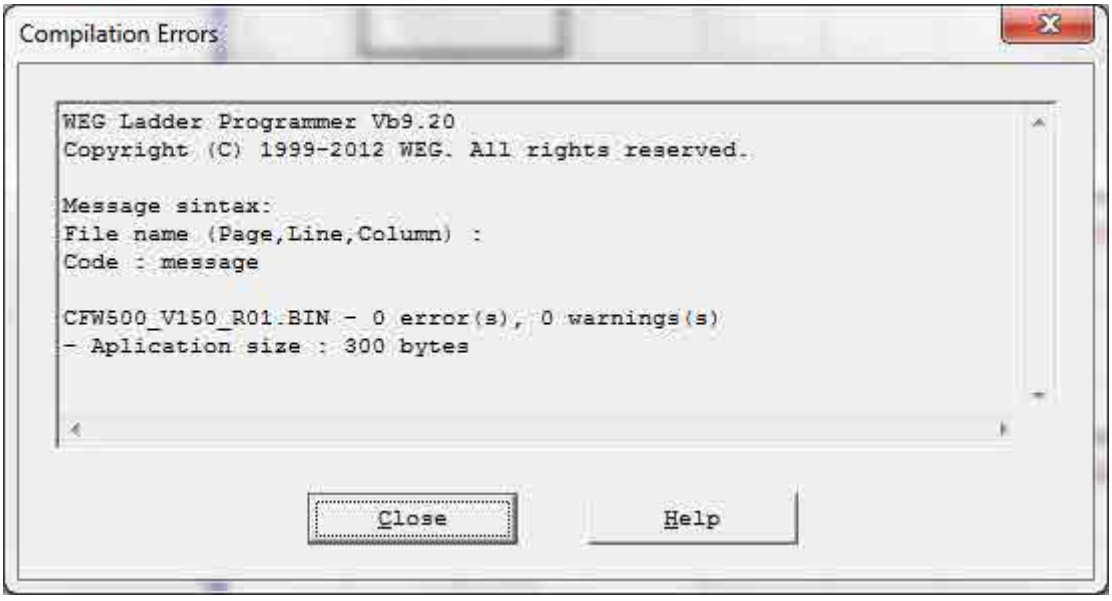
- Parameter descriptive text (up to 21 characters);
- Unit selection;
- Minimum and maximum limit;
- Number of decimal positions;
- Hexadecimal or normal format;
- Reading or writing only;
- Modification only with a stopped motor or online;
- With or without sign;
- Ignores the password (allows modification regardless of the inverter password (P0000)) or normal;
- Displays or hides the parameter;
- Allows saving the parameter value (retentive), when it is used in some blocks (PLC, Calculations and Transfers) on power down;
- Configuration parameter which allows modification with the motor running.

Those configurations can be transferred to the CFW500 with the “Download” button.



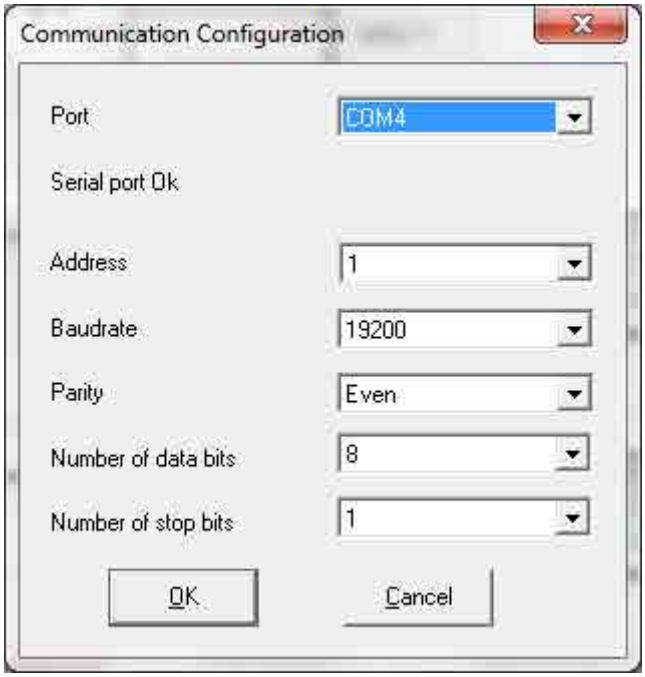
5.6 CONSTRUCT – COMPILE

It analyzes the application and generates the compiled code for the specified equipment.



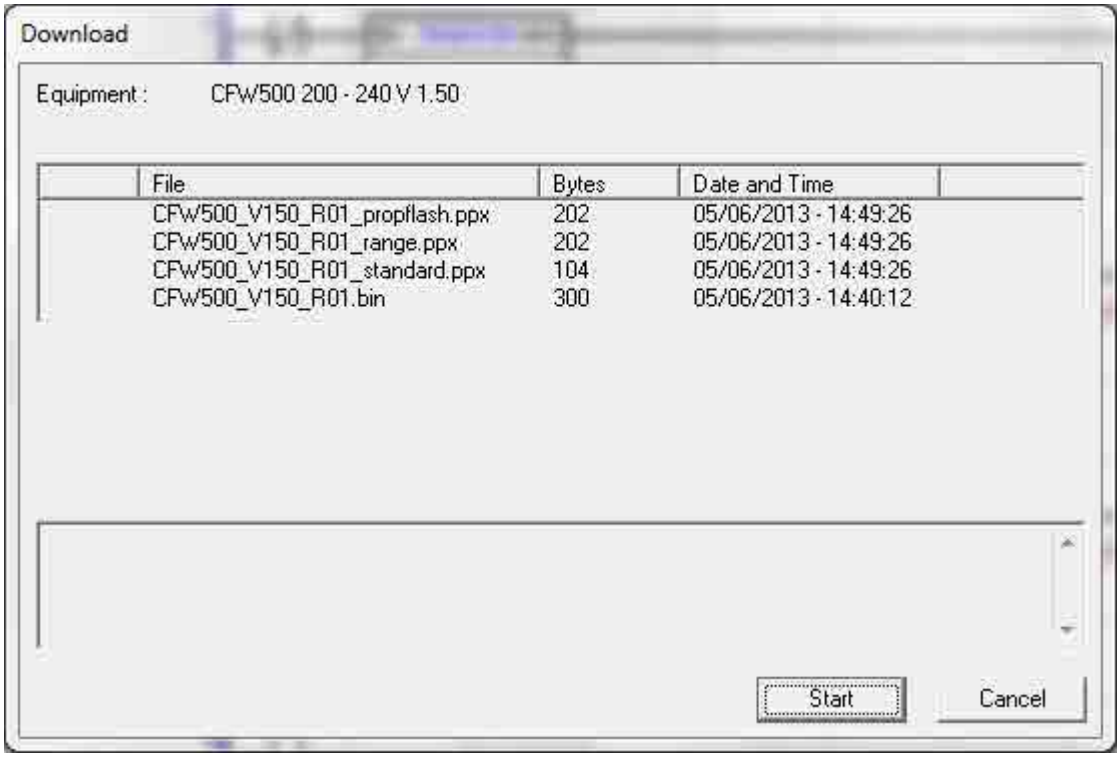
5.7 COMMUNICATION – CONFIGURATION

The Serial port is used for the CFW500.



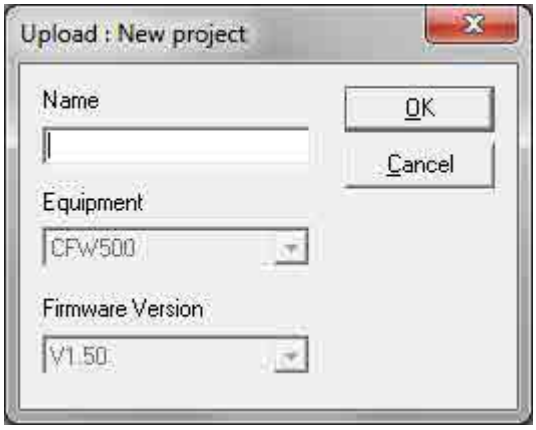
5.8 COMMUNICATION – DOWNLOAD

This command allows downloading the application and/or user parameter configurations to the CFW500.



5.9 COMMUNICATION – UPLOAD

This command makes it possible to upload and open the application installed on the CFW500, provided that the password is valid.


Upload : New project
Name
OK
Cancel
Equipment
CFW500
Firmware Version
V1.50

6 ALARMS, FAULTS AND POSSIBLE CAUSES

Table 6.1: *"Alarms", "Faults" and possible causes*

Fault/Alarm	Description	Possible Causes
A702: Inverter Disabled	It occurs when a movement block (REF Block) is active and the drive general enabling command is not active.	■ Check if the drive general enabling command is active.
A704: Two Movem. Enabled	It occurs when 2 or more movement blocks (REF Block) are enabled simultaneously.	■ Check the user program logic.
A706: Not Prog. Ref. SPLC	It occurs when a movement block is enabled and the speed reference is not programmed for the SoftPLC	■ Check the programming of the references in the local and/or remote modes (P221 and P222).

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